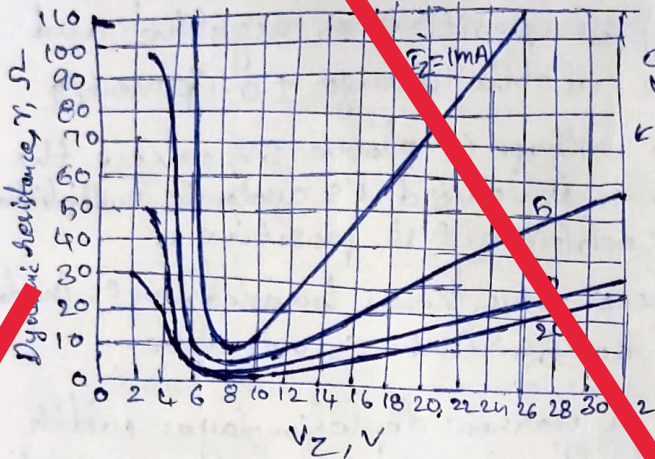


→ Therefore the value of avalanche voltage must increase with increased temperature.

→ Dynamic Resistance and Capacitance

→ For a Zener diode, if the reciprocal slope $\Delta V_Z / \Delta I_Z$, called dynamic resistance, is r , then a change ΔI_Z in the operating current of the diode produces a change $\Delta V_Z = r \Delta I_Z$ in the operating voltage.

→ Ideally, $r = 0$, corresponding to a volt-ampere curve which, in the breakdown region, is precisely vertical.



Dynamic resistance at a number of currents for Zener diodes of different operating voltages at 25°C

→ The broader minimum occurs in the range 6 to 10 V, and at large V_Z and small I_Z , the

dynamic resistance r may become quite large.

→ The capacitance across a breakdown diode is the transition capacitance and hence varies inversely as some power of voltage.

→ Since C_T is proportional to cross-sectional area of the diode, high-power avalanche diodes have very large capacitances.

→ Values of C_T from 10 to 10,000 pF are common.

P-n Junction as a Rectifier

→ One of the important applications of the diode is the rectifier circuits.

→ These circuits are used to convert the a.c. i/p of the normal available power supply into a d.c. o/p.

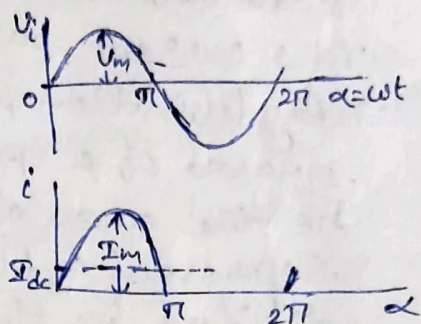
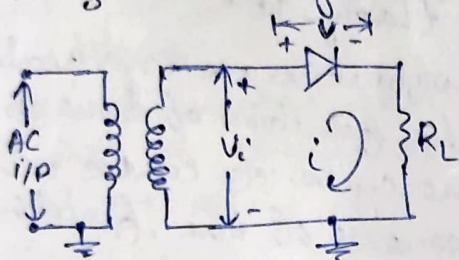
→ The d.c. source of power is an important requirement in almost all electronic systems like televisions, stereos and computers.

→ However, the o/p of a rectifier circuit always contains some a.c. components.

→ Filtering techniques are employed to remove the harmonic ac components from the rectified o/p to obtain a more accurate dc o/p.

A Half-Wave Rectifier

- Any electrical device which offers a low resistance to current in one direction but a high resistance to current in opposite direction is called a rectifier.
- Such a device is capable of converting a sinusoidal i/p waveform, whose average value is zero, into a unidirectional (though not const.) waveform, with a non-zero average component.



- The rectifying device is usually a semiconductor diode (or for very high voltages, a vacuum-tube diode)
- From the piecewise linear approximation for the diode the device has essentially infinite resistance in the reverse direction (for $V < V_f$) and a small and constant resistance R_f in the forward direction (for $V > V_f$)
- Since in the rectifier circuit, the i/p $V_i = V_m \sin \omega t$ has a peak value V_m which is very large compared with the offset voltage V_f
- We assume $V_f = 0$. Subject to this idealization of the diode characteristic, the current in the diode or load R_L is given by

$$i = I_m \sin \alpha \quad \text{where } 0 \leq \alpha \leq \pi$$

$$i = 0 \quad \text{where } \pi \leq \alpha \leq 2\pi$$

$$\text{where } \alpha = \omega t, \quad I_m = \frac{V_m}{R_f + R_L}$$

- The o/p current is unidirectional and has a non-zero average value.

→ Reading of a dc Ammeter

- A dc ammeter is calibrated so that the needle deflection indicates the average value of the current passing through it.

→ By definition, the average value of a periodic function is given by the area of one cycle of the curve divided by the base

→ Mathematically
$$I_{dc} = \frac{1}{2\pi} \int_0^{2\pi} i \, d\alpha$$

→ For half-wave circuit

$$I_{dc} = \frac{1}{2\pi} \int_0^{\pi} I_m \sin \alpha \, d\alpha = \frac{I_m}{\pi}$$

→ Reading of an ac Ammeter

→ An ac ammeter is constructed so that the needle deflection indicates the effective or rms current passing through it.

→ By definition, the effective or rms value squared of a periodic function of time is given by the area of one cycle of curve which represents the square of the function, divided by the base

→ Mathematically
$$I_{rms} = \left(\frac{1}{2\pi} \int_0^{2\pi} i^2 \, d\alpha \right)^{1/2}$$

→ For half-wave circuit

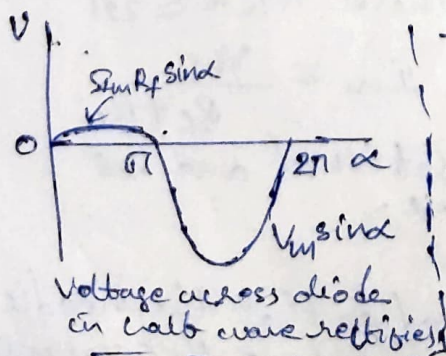
$$I_{rms} = \left(\frac{1}{2\pi} \int_0^{\pi} I_m^2 \sin^2 \alpha \, d\alpha \right)^{1/2} = \frac{I_m}{\sqrt{2}}$$

→ The rms value of a sinusoidal wave is $\frac{I_m}{\sqrt{2}}$

→ Reading of a dc Voltmeter

→ This instrument reads the average value of the voltage across its terminals.

→ If the voltmeter is across diode, the instantaneous diode voltage must be plotted, and the area under one cycle of the curve must be found.



→ When diode is conducting, it has a resistance R_f , and voltage across it is $i R_f$

→ When diode is non-conducting, the current is zero, and the transformer secondary voltage V_s appears across the diode.

→ Thus

$$v = iR_f = I_m R_f \sin \alpha, \quad 0 \leq \alpha \leq \pi$$

$$v = V_m \sin \alpha, \quad \pi \leq \alpha \leq 2\pi$$

→ The reading of the dc voltmeter is

$$V_{dc} = \frac{1}{2\pi} \left(\int_0^{\pi} I_m R_f \sin \alpha \, d\alpha + \int_{\pi}^{2\pi} V_m \sin \alpha \, d\alpha \right)$$

$$= \frac{1}{\pi} (I_m R_f - V_m) = \frac{1}{\pi} [I_m R_f - I_m (R_f + R_L)]$$

$$V_{dc} = - \frac{I_m R_L}{\pi}$$

→ This result is negative, which means that if the voltmeter is to read upscale, its positive terminal must be connected to cathode of the diode.

→ The voltmeter reading does not equal the product of the direct current I_{dc} times the diode resistance R_f .

→ The reason is that diode is a non-linear device whose resistance is constant (and equals R_f) only when the anode voltage is positive.

→ The dc voltage across the load does equal the product of direct current I_{dc} times the output resistance R_L because the load is a truly constant resistor.

→ Reading of a Wattmeter

→ This instrument is built to indicate the average value of the product of the instantaneous current through its current coil and the instantaneous voltage across its potential coil.

→ Hence the power read by a wattmeter, whose voltage coil is placed across the transformer secondary, is

$$P_i = \frac{1}{2\pi} \int_0^{2\pi} v_i i \, d\alpha$$

$$\text{Since } v_i = i(R_f + R_L) \text{ for } 0 \leq \alpha \leq \pi$$

$$P_i = \frac{1}{2\pi} \int_0^{2\pi} i^2 (R_f + R_L) \, d\alpha$$

$$= \frac{1}{2\pi} \int_0^{\pi} I_m^2 \sin^2 \alpha (R_f + R_L) \, d\alpha$$

$$P_i = I_{rms}^2 (R_f + R_L)$$

→ Peak Inverse Voltage

→ For each rectifier circuit there is a max. voltage to which the diode is subjected.

- This potential is called peak inverse voltage, because it occurs during that part of the cycle when the diode is non-conducting.
- For the half-wave ckt (without a diode) the peak inverse voltage is V_m , the peak transformer secondary voltage.

Regulation

- The variation of dc o/p voltage as a function of dc load current is called regulation.
- The percentage regulation is defined as

$$\% \text{ regulation} = \frac{V_{\text{no load}} - V_{\text{full load}}}{V_{\text{full load}}} \times 100\%$$
- For an ideal power supply, the o/p voltage is independent of the load (the o/p current) & the regulation is zero
- The variation of V_{dc} with I_{dc} for half-wave rectifiers is obtained as follows:

$$I_{dc} = \frac{I_m}{\pi} = \frac{V_m / \pi}{R_f + R_L}$$

$$\begin{aligned} V_{dc} &= I_{dc} R_L = I_{dc} (R_f + R_L) - I_{dc} R_f \\ &= \frac{I_m (R_f + R_L)}{\pi} - I_{dc} R_f = \frac{V_m}{\pi} - I_{dc} R_f \end{aligned}$$

- This result shows that V_{dc} equals $\frac{V_m}{\pi}$ at no load and the dc voltage decreases linearly with an increase in dc o/p current.
- The larger the magnitude of the diode forward resistance, the greater is this decrease for a given current change.
- The effective internal resistance of the power supply is R_f
- In practice, the resistance R_s of the transformer secondary is in series with the diode and R_s should be added to R_f in $V_{dc} = \frac{V_m}{\pi} - I_{dc} R_f$
- Consider a 12V 100 mA supply with $R_f + R_s = 20 \Omega$. The no-load voltage is 12V, the full load voltage is $12 - (0.1)(20) = 10V$, the percentage regulation is $\frac{12 - 10}{10} \times 100 = 20\%$.

→ Power-supply Specifications

- The most important characteristics which must be specified for a power supply are the following:
- 1) The required o/p dc voltage
 - 2) The regulation
 - 3) The average and peak currents in each diode
 - 4) The peak reverse voltage of each diode
 - 5) The ripple factor

→ Ripple Factor

→ The purpose of a rectifier is to convert alternating into direct current.

→ In the conversion from an alternating current into a unidirectional current, periodically fluctuating components still remaining on the o/p wave

→ It is for this reason that filters are frequently used in order to decrease these ac components.

→ A measure of the fluctuating components is given by the ripple factor r , which is defined as

$$r \equiv \frac{\text{rms value of alternating components of wave}}{\text{average value of wave}}$$

$$r \equiv \frac{I_{rms}}{I_{dc}} \equiv \frac{V_{rms}}{V_{dc}} \quad \text{--- (1)}$$

where the terms I_{rms} and V_{rms} denote the rms value of ac components of current and voltage respectively.

→ By noting the instantaneous ac component of current is given by $i' = i - I_{dc}$

$$\text{then } I_{rms} \equiv \sqrt{\frac{1}{2\pi} \int_0^{2\pi} (i')^2 dx}$$

$$= \sqrt{\frac{1}{2\pi} \int_0^{2\pi} (i - I_{dc})^2 dx}$$

$$= \sqrt{\frac{1}{2\pi} \int_0^{2\pi} (i^2 - 2iI_{dc} + I_{dc}^2) dx}$$

$$= \sqrt{I_{rms}^2 - 2I_{dc}^2 + I_{dc}^2} \quad \left(\because \frac{1}{2\pi} \int_0^{2\pi} i dx = I_{dc} \right)$$

→ The ripple current

$$I_{rms} = \sqrt{I_{rms}^2 - I_{dc}^2} \quad \text{--- (2)}$$

→ Combining (1) & (2) $r = \frac{\sqrt{I_{rms}^2 - I_{dc}^2}}{I_{dc}}$

$$r = \sqrt{\left(\frac{I_{rms}}{I_{dc}}\right)^2 - 1}$$

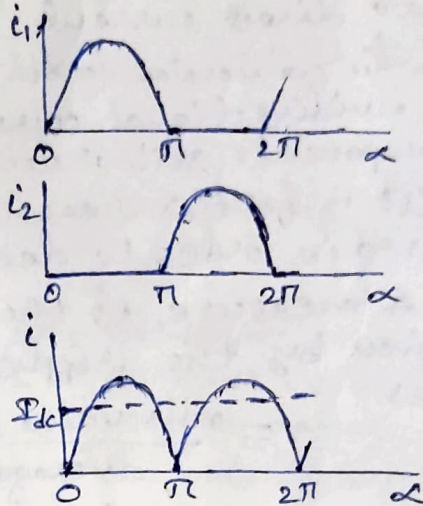
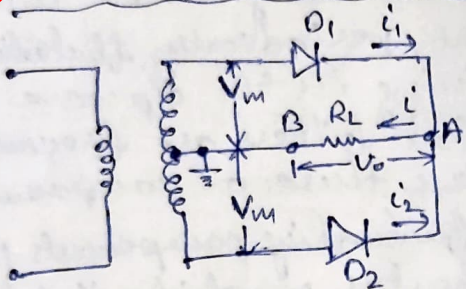
→ For the half-wave rectifiers, the ratio

$$\frac{I_{rms}}{I_{dc}} = \frac{I_m/2}{I_m/\pi} = \frac{\pi}{2} = 1.57$$

Hence $r = \sqrt{(1.57)^2 - 1} = 1.21$

→ This result indicates that the rms ripple voltage exceeds the dc off voltage & shows that the half-wave rectifier is a relatively poor ckt for converting alternating into direct current.

Full-Wave Rectifier



→ The ckt of a full-wave rectifier comprise two half-wave ckt which are so connected that conduction takes place through one diode during one half of the power cycle & through the other diode during the second-half of the power cycle.

→ The current to the load is the sum of these two currents.

→ The dc and rms values of the load current in such a system from the definitions are bound to be

$$I_{dc} = \frac{2I_m}{\pi}$$

$$I_{rms} = \frac{I_m}{\sqrt{2}}$$

where $I_m = \frac{V_m}{R_f + R_L}$

and V_m is the peak transformer secondary voltage from an end to the center tap.

→ The direct current supplied to the load for full-wave connection is twice that for the half-wave ckt

→ The i/p power supplied to the ckt in full-wave case is given by same expression as for half-wave case

$$P_i = I_{rms}^2 (R_f + R_L)$$

→ Ripple Factor

→ The required current ratio that appears in expression for ripple factor is

$$\frac{I_{rms}}{I_{dc}} = \frac{I_m/\sqrt{2}}{2I_m/\pi} = 1.11$$

→ The ripple factor for full-wave ckt is

$$r = \sqrt{(1.11)^2 - 1} = 0.482$$

→ Regulation

→ The dc o/p voltage is given by $V_{dc} = \frac{2V_m}{\pi} - I_{dc}R_f$

→ Peak Inverse Voltage

→ At the instant of time when transformer secondary voltage to midpoint is at its peak value V_m , diode D_1 is conducting and D_2 is non-conducting

→ If we apply KVL around the outside loop and neglect the small voltage drop across D_1 , we obtain $2V_m$ for the peak inverse voltage across D_2 .

→ This result is obtained without reference to the nature of the load, which can be a pure resistance R_L or a combination of R_L and some reactive elements which may be introduced to filter the ripple.

→ So in a full-wave ckt, independently of the filter used, the peak inverse voltage across each diode is twice the maximum voltage measured from midpoint to either end.

→ Bridge Rectifier

→ The full-wave rectifier ckt requires a center-tapped transformer where only one half of the total ac voltage of transformer secondary winding is utilized to convert into dc o/p.

→ Now we consider a different configuration of the full-wave ckt, called bridge rectifier, where the entire ac voltage of transformer secondary is used to convert into the dc voltage.